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# WR

## Product Line-up

Autonomous Mobile Robots  
Autonomous Mobile Manipulator Robots  
Robot Hand



## Product Line-up

**01**

### **AMR Payload 300kg**

- WR300CV
- WR300LD
- WR300CB
- WR300LF

**02**

### **AMR Payload 600kg**

- WR600LF

**03**

### **AMR Payload 1,000kg**

- WR1000LF

**04**

### **Autonomous Mobile Manipulator Robots**

- Differential wheel  
WR300M-TM, WR300M-RB
- Mecanum wheel  
WR300MM-TM, WR300MM-NU

**05**

### **AMR Control System**

- WR-ACS

**06**

### **Allegro Hand**

- Version 4(4 Fingers Hand)
- Version 5(3 Fingers Hand)
- Version 5(4 Fingers Hand) Plus



# WR300CV

Internal Transportation Platform  
with Conveyor System

## Specification

Item	Contents	Specifications
Robot Basic Specification	Navigation Type Dimension(W x L x H, mm) Payload(kg) Driving System Wheel(Material, Size) Loading Method Equipment Docking Method	SLAM 630 x 825 x 890mm 300kg Differential Drive Urethane, Driving 6"(15cm) x 2, Sub" x 4 Auto Conveyor Front or Side Docking
Performance	Stop Accuracy Docking Accuracy(V Marker) Operation Time Minimum Driving Aisle Width Max Speed(m/sec) Average Speed(m/sec) Rotating Diameter Max. Rotation Speed(radian/sec) Maximum Slope(Max Payload Condition)	± 20mm ± 10mm 12h(No Payload), 10h(Full Payload) 930 mm 1.2m/sec About 0.7m/sec 1,036mm 0.5 Max. 5°
Safety & Sensor Device	Emergency Button LiDAR Camera Minimum Obstacle Detection Size	Up to 2ea Sick TIM561 or TIM571 2ea Intel Realsense 3D Depth Camera(2ea : Front) 30mm
Alarm Sound & LED	Alarm Warning & Status Indication	Sound & LED LED & Buzzer
Battery & Charging Station	Battery Type, Capacity Battery Monitoring Charging Time Charging Method Charger Power(In/Out) Charging Station Size	Li-Ion, DC24V / 50Ah SOC, SOH, Temp, Remaining Capacity, Available Energy About 1~1.5Hr Autonomous Docking / Manual AC110~220V 10A / DC 29V 45A 575 x 320 x 760mm
Environment	Ambient Operating Temperature(°C) Floor Requirements	0 to +40 No Water, No Oil, No Dirt
Communication	Network Equipment Communication	WIFI 2.4Ghz, 5GHz LTE/5G Support(Optional) Hybrid PIO





# WR300LD

Internal Transportation Platform  
for Semi-Automated Factory

## Specification

Item	Contents	Specifications
Robot Basic Specification	Navigation Type Dimension(W x L x H, mm) Payload(kg) Driving System Wheel(Material, Size) Loading Method Moving Method	SLAM 630 x 825 x 1,600mm 300kg Differential Drive Urethane, Driving 6"(15cm) x 2, Sub" x 4 Manual LCD touch
Performance	Stop Accuracy Docking Accuracy(V Marker) Operation Time Minimum Driving Aisle Width Max Speed(m/sec) Average Speed(m/sec) Rotating Diameter Max. Rotation Speed(radian/sec) Maximum Slope(Max Payload Condition)	± 20mm ± 10mm 12h(No Payload), 10h(Full Payload) 930mm 1.2m/sec About 0.7m/sec 1,036 mm 0.5 Max. 5°
Safety & Sensor Device	Emergency Button LiDAR Camera Minimum Obstacle Detection Size	Up to 2ea Sick TIM561 or TIM571 2ea Intel Realsense 3D Depth Camera(2ea : Front) 30mm
Alarm Sound & LED	Alarm Warning & Status Indication Display	Sound & LED LED & Buzzer LCD Touch
Battery & Charging Station	Battery Type, Capacity Battery Monitoring Charging Time Charging Method Charger Power(In/Out) Charging Station Size	Li-Ion, DC24V / 50Ah SOC, SOH, Temp, Remaining Capacity, Available Energy About 1~1.5Hr Autonomous Docking / Manual AC110~220V 10A / DC 29V 45A 575 x 320 x 760mm
Environment	Ambient Operating Temperature(°C) Floor Requirements	0 to +40 No Water, No Oil, No Dirt
Communication	Network	WIFI 2.4Ghz, 5GHz LTE/5G Support(Optional)



# WR300CB

Internal Transportation Platform  
for Semi-Automated Factory

## Specification

Item	Contents	Specifications
Robot Basic Specification	Navigation Type Dimension(W x L x H, mm) Payload(kg) Driving System Wheel(Material, Size) Loading Method Moving Method	SLAM 630 x 825 x 940mm 300kg Differential Drive Urethane, Driving 6"(15cm) x 2, Sub" x 4 Manual LCD touch or Joystick
Performance	Stop Accuracy Docking Accuracy(V Marker) Operation Time Minimum Driving Aisle Width Max Speed(m/sec) Average Speed(m/sec) Rotating Diameter Max. Rotation Speed(radian/sec) Maximum Slope(Max Payload Condition)	± 20mm ± 10mm 12h(No Payload), 10h(Full Payload) 930mm 1.2m/sec About 0.7m/sec 1,036mm 0.5 Max. 5°
Safety & Sensor Device	Emergency Button LiDAR Camera Minimum Obstacle Detection Size	Up to 2ea Sick TIM561 or TIM571 2ea Intel Realsense 3D Depth Camera (2ea : Front) 30mm
Alarm Sound & LED	Alarm Warning & Status Indication Display	Sound & LED LED & Buzzer LCD Touch
Battery & Charging Station	Battery Type, Capacity Battery Monitoring Charging Time Charging Method Charger Power(In/Out) Charging Station Size	Li-Ion, DC24V / 50Ah SOC, SOH, Temp, Remaining Capacity, Available Energy About 1~1.5Hr Autonomous Docking / Manual AC110~220V 10A / DC 29V 45A 575 x 320 x 760mm
Environment	Ambient Operating Temperature(°C) Floor Requirements	0 to +40 No Water, No Oil, No Dirt
Communication	Network	WIFI 2.4Ghz, 5GHz LTE/5G Support(Optional)

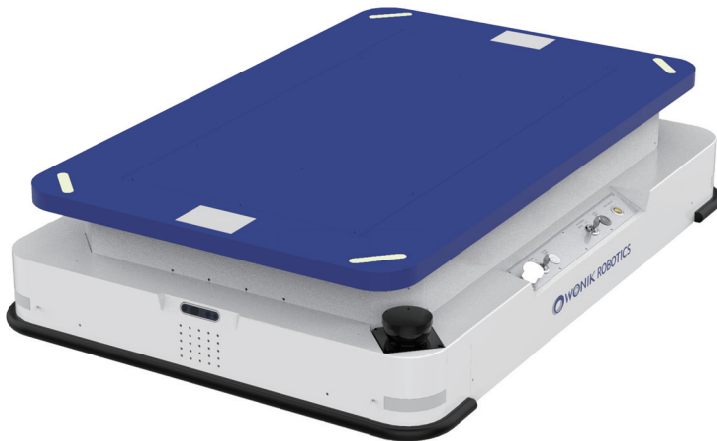


# WR300LF

Internal Cart Transportation  
Platform with Hook Lift

## Specification

Item	Contents	Specifications
Robot Basic Specification	Navigation Type Dimension(W x L x H, mm) Payload(kg) Driving System Wheel(Material, Size) Loading Method	SLAM 630 x 825 x 450mm 300kg Differential Drive Urethane, Driving 6"(15cm) x 2, Sub" x 4 Lift
Performance	Stop Accuracy Docking Accuracy(V Marker) Operation Time Minimum Driving Aisle Width Max Speed(m/sec) Average Speed(m/sec) Rotating Diameter Max. Rotation Speed(radian/sec) Maximum Slope(Max Payload Condition)	± 20mm ± 10mm 12h(No Payload), 10h(Full Payload) 930mm 1.2m/sec About 0.7m/sec 1,036 mm 0.5 Max. 5°
Safety & Sensor Device	Emergency Button LiDAR Camera Minimum Obstacle Detection Size	Up to 3ea Sick TIM561 or TIM571 2ea Intel Realsense 3D Depth Camera(2ea : Front) 30mm
Alarm Sound & LED	Alarm Warning & Status Indication	Sound & LED LED & Buzzer
Battery & Charging Station	Battery Type, Capacity Battery Monitoring Charging Time Charging Method Charger Power(In/Out) Charging Station Size	Li-Ion, DC24V / 50Ah SOC, SOH, Temp, Remaining Capacity, Available Energy About 1~1.5Hr Autonomous Docking / Manual AC110~220V 10A / DC 29V 45A 575 x 320 x 760mm
Environment	Ambient Operating Temperature(°C) Floor Requirements	0 to +40 No Water, No Oil, No Dirt
Communication	Network	WIFI 2.4Ghz, 5GHz LTE/5G Support(Optional)



## WR600LF

Low-height and Heavy Rated Load  
AMR with Pallet Lift Module

### Specification

Item	Contents	Specifications
Robot Basic Specification	Navigation Type Dimension(W x L x H, mm) Payload(kg) Driving System Wheel(Material, Size) Loading Method	SLAM 920 x 1,310 x 318mm(/W Lift Module) 600kg Differential Type Urethane, Driving 6"(15cm) x 2, Sub" x 4 Pallet Lift(Stroke 100mm)
Performance	Stop Accuracy Docking Accuracy(V Marker) Operation Time Minimum Driving Aisle Width Max Speed(m/sec) Average Speed(m/sec) Rotating Diameter Max. Rotation Speed(radian/sec) Maximum Slope(Max Payload Condition)	± 20mm ± 10mm 12h(No Payload), 10h(Full Payload) 1,450mm 1m/sec About 0.7m/sec 1,618mm 0.5 Max. 3.0°
Safety & Sensor Device	Emergency Button LiDAR Camera Minimum Obstacle Detection Size	Up to 2ea Sick Nano Scan3 Safety System(2ea) Intel Realsense 3D Depth Camera(2ea : Front & Rear) 30mm
Indicator	Alarm Warning & Status Indication	Sound & LED LED & Buzzer
Battery & Charging Station	Battery Type, capacity Battery Monitoring Charging Time Charging Method Charger Power(In/Out) Charging Contact Type Charging Station Size	Li-Ion, DC50V 50Ah(Detachable) SOC, SOH, Temp, Remaining Capacity, Available Energy About 1~1.5Hr Autonomous Dock / Manual AC110~220V 10A / DC 59V 45A Automatic Sliding Push Type 705 x 400 x 450mm
Environment	Ambient Operating Temperature(°C) Floor Requirements	0 to +40 No Water, No Oil, No Dirt
Communication	Network	WIFI 2.4Ghz, 5GHz LTE/5G Support(Optional)



## WR1000LF

Low-hight and Heavy Rated Load  
AMR with Pallet Lift Module

### Specification

Item	Contents	Specifications
Robot Basic Specification	Navigation Type Dimension (W x L x H, mm) Payload(kg) Driving System Wheel(Material, Size) Loading Method	SLAM 956 x 1,350 x 318mm(/W Lift Module) 1,000kg Differential Drive Urethane, Driving 8"(20cm) x 2, Sub" x 4 Pallet Lift(Stroke 100mm)
Performance	Stop Accuracy Docking Accuracy(V Marker) Operation Time Minimum Driving Aisle Width Max Speed(m/sec) Average Speed(m/sec) Rotating Diameter Max. Rotation Speed(radian/sec) Maximum Slope(Max Payload Condition)	± 20mm ± 10mm 12h(No Payload), 10h(Full Payload) 1,450mm 1.0m/sec About 0.7m/sec 1,618mm 0.5 Max. 5°
Safety & Sensor Device	Emergency Button LiDAR Camera Minimum Obstacle Detection Size	Up to 2ea Sick Nano Scan3 Safety System(2ea) Intel Realsense 3D Depth Camera(2ea : Front) 30mm
Alarm Sound & LED	Alarm Warning & Status Indication	Sound & LED LED & Buzzer
Battery & Charging Station	Battery Type, Capacity Battery Monitoring Charging Time Charging Method Charger Power(In/Out) Charging Contact Type Charging Station Size	Li-Ion, DC24V / 50Ah SOC, SOH, Temp, Remaining Capacity, Available Energy About 1~1.5Hr Autonomous Docking / Manual AC110~220V 10A / DC 29V 45A Automatic Sliding Push Type 705 x 400 x 450mm
Environment	Ambient Operating Temperature(°C) Floor Requirement	0 to +40 No Water, No Oil, No Dirt
Communication	Network	WIFI 2.4Ghz, 5GHz LTE/5G Support(Optional)



## WR300M-TM

Autonomous Mobility Platform  
with Cobots

### Specification

Item	Contents	Specifications
Robot Basic Specification	Navigation Type Dimension(W x L x H, mm) Payload(kg) Driving System Wheel(Material, Size) Manipulator	SLAM 630 x 825 x 680mm(Mobile Platform) 100Kg(Mobile Platform, /w Manipulator) Differential Drive Urethane, Driving 6"(15cm) x 2, Sub" x 4 TM Manipulator(TM12) - Payload : 12kg - Reach : 1,300mm
Performance	Stop Accuracy Docking Accuracy(V Marker) Operation Time Minimum Driving Aisle Width Max Speed(m/sec) Average Speed(m/sec) Rotating Diameter Max. Rotation Speed(radian/sec) Maximum Slope(Max Payload Condition)	± 20mm ± 10mm About 6h 930mm 1.2m/sec About 0.7m/sec 1,036mm 0.5 Max. 5°
Safety & Sensor Device	Emergency Button LiDAR Camera Minimum Obstacle Detection Size	Up to 2ea Sick TIM561 or TIM571 2ea Intel Realsense 3D Depth Camera(2ea : Front) 30mm
Alarm Sound & LED	Alarm Warning & Status Indication	Sound & LED LED & Buzzer
Battery & Charging Station	Battery Type, Capacity Battery Monitoring Charging Time Charging Method Charger Power(In/Out) Charging Station Size	Li-Ion, DC24V / 50Ah SOC, SOH, Temp, Remaining Capacity, Available Energy About 1~1.5Hr Autonomous Docking / Manual AC110~220V 10A / DC 29V 45A 575 x 320 x 760mm
Environment	Ambient Operating Temperature(°C) Floor Requirement	0 to +40 No Water, No Oil, No Dirt
Communication	Network	WIFI 2.4Ghz, 5GHz with External Patch Ant. LTE/5G Support(Optional)



## WR300M-RB

Autonomous Mobility Platform  
with Cobots

### Specification

Item	Contents	Specifications
Robot Basic Specification	Navigation Type Dimension(W x L x H, mm) Payload(kg) Driving System Wheel(Material, Size) Manipulator	SLAM 630 x 825 x 680mm(Mobile Platform) 100kg(Mobile Platform, /w Manipulator) Differential Drive Urethane, Driving 6"(15cm) x 2, Sub" x 4 Rainbow Robotics Manipulator - Payload : 12kg - Reach : 1,300mm
Performance	Stop Accuracy Docking Accuracy(V Marker) Operation Time Minimum Driving Aisle Width Max Speed(m/sec) Average Speed(m/sec) Rotating Diameter Max. Rotation Speed(radian/sec) Maximum Slope(Max Payload Condition)	± 20mm ± 10mm About 6h 930mm 1.0m/sec About 0.7m/sec 1,036mm 0.5 Max. 5°
Safety & Sensor Device	Emergency Button LiDAR Camera Minimum Obstacle Detection Size	Up to 2ea Sick TIM561 or TIM571 2ea Intel Realsense 3D Depth Camera(2ea : Front) 30mm
Alarm Sound & LED	Alarm Warning & Status Indication	Sound & LED LED & Buzzer
Battery & Charging Station	Battery Type, Capacity Battery Monitoring Charging Time Charging Method Charger Power(In/Out) Charging Station Size	Li-Ion, DC24V / 50Ah SOC, SOH, Temp, Remaining Capacity, Available Energy About 1~1.5Hr Autonomous Docking / Manual AC110~220V 10A / DC 29V 45A 575 x 320 x 760mm
Environment	Ambient Operating Temperature(°C) Floor Requirement	0 to +40 No Water, No Oil, No Dirt
Communication	Network	WIFI 2.4Ghz, 5GHz with External Patch Ant. LTE/5G Support(Optional)





## WR300MM-TM

Autonomous and Flexible Mobility  
Platform with Cobots

### Specification

Item	Contents	Specifications
Robot Basic Specification	Navigation Type Dimension(W x L x H, mm) Payload(kg) Driving System Wheel(Material, Size) Manipulator	SLAM 700 x 950 x 810mm(Mobile Platform) 100kg(Mobile Platform, /w Manipulator) Mecanum Wheel Urethane, Driving 6"(15cm) x 2, Sub" x 4 TM Manipulator(TM12) - Payload : 12kg - Reach : 1,300mm
Performance	Stop Accuracy Docking Accuracy Operation Time Minimum Aisle Width Max Speed(m/sec) Average Speed(m/sec) Rotating Diameter Max. Rotation Speed(radian/sec) Maximum Slope(Max Payload Condition)	± 10mm ± 5mm About 6h 850mm 0.6m/sec About 0.5m/sec 1,038mm 0.5 Max. 2°
Safety & Sensor Device	Emergency Button LiDAR Camera Minimum Obstacle Detection Size	Up to 2ea Sick Nano Scan3 Safety System(2ea) Intel Realsense 3D Depth Camera(2ea : Front & Rear) 30mm
Indicator	Alarm Warning & Status Indication Display	Sound & LED LED & Buzzer LCD Touch
Battery & Charging Station	Battery Type, Capacity Battery Monitoring Charging Time Charging Method  Charger Power(In/Out)	Li-Ion, DC50V / 50Ah SOC, SOH, Temp, Remaining Capacity, Available About 1~1.5Hr Need with Battery Change Unit Automatic Change time : about 50s Replacable Battery / Manual AC110~220V 10A / DC 59V 45A
Environment	Ambient Operating Temperature(°C) Floor Requirements	0 to +40 No Water, No Oil, No Dirt
Communication	Network	WIFI 2.4Ghz, 5GHz with External Patch Ant. LTE/5G Support(Optional)



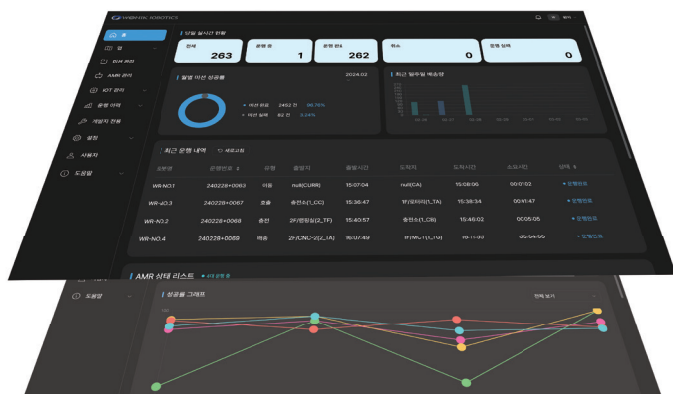


## WR300MM-NU

Autonomous and Flexible Mobility Platform with Cobots

### Specification

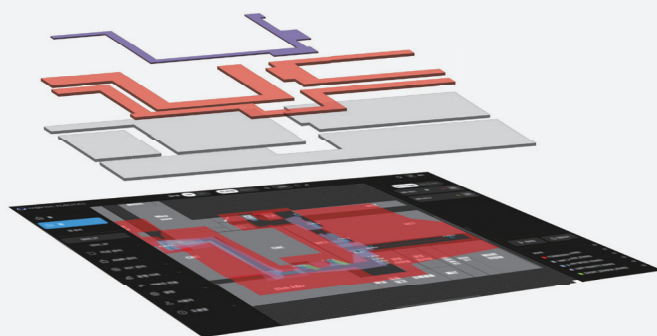
Item	Contents	Specifications
Robot Basic Specification	Navigation Type Dimension(W x L x H, mm) Payload(kg) Driving System Wheel(Material, Size) Manipulator	SLAM 700 x 950 x 810mm(Mobile Platform) 100kg(Mobile Platform, /w Manipulator) Mecanum Wheel Urethane, Driving 6"(15cm) x 2, Sub" x 4 NEUROMEKA Nuri12 - Payload : 12kg - Reach : 1,434mm
Performance	Stop Accuracy Docking Accuracy Operation Time Minimum Aisle Width Max Speed(m/sec) Average Speed(m/sec) Rotating Diameter Max. Rotation Speed(radian/sec) Maximum Slope(Max Payload Condition)	± 10mm ± 5mm About 4h 850 mm 0.6m/sec About 0.5m/sec 1,038mm 0.5 Max. 2°
Safety & Sensor Device	Emergency Button LiDAR Camera Minimum Obstacle Detection Size	Up to 2ea Sick Nano Scan3 Safety System(2ea) Intel Realsense 3D Depth Camera(2ea : Front & Rear) 30mm
Alarm Sound & LED	Alarm Warning & Status Indication Display	Sound & LED LED & Buzzer LCD Touch
Battery & Charging Station	Battery Type, Capacity Battery Monitoring Charging Time Charging Method  Charger Power(In/Out)	Li-Ion, DC50V / 50Ah SOC, SOH, Temp, Remaining Capacity, Available About 1~1.5Hr Need with Battery Change Unit Automatic Change time : about 50s Replacable Battery / Manual AC110~220V 10A / DC 59V 45A
Environment	Ambient Operating Temperature(°C) Floor Requirements	0 to +40 No Water, No Oil, No Dirt
Communication	Network	WIFI 2.4Ghz, 5GHz with External Patch Ant. LTE/5G Support(Optional)



## WR-ACS

The AMR Real-time Integrated Control System manages and controls up to 100 robots simultaneously in real-time, enabling efficient operational management through linkage with higher-level systems such as ERP and MES.

### Key Features of WR-ACS

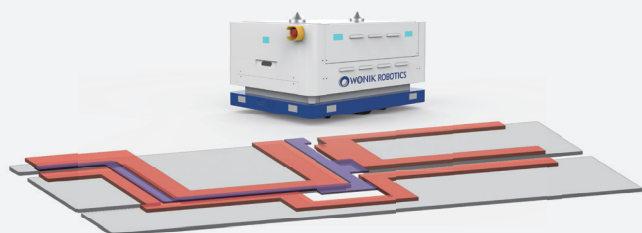


#### Web-based Responsive Control System

Real-time monitoring of AMR operation history and easy data access for operational details.

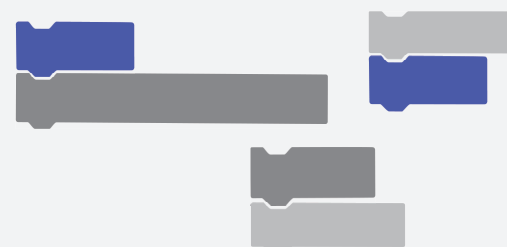
#### Map Edition Function

Customizable robot routes, traffic control, and movements, adjustable to specific operational conditions for enhanced convenience and flexibility.



#### Geofencing-based Mission Settings

Real-time automated management of multiple AMR groups, enabling efficient operational management based on predefined area conditions.



#### Scratch-based Mission Configuration

Easily assign missions to AMRs using the Scratch framework, enhancing productivity through simplified task creation.

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2022090060	2022-09-01 10:04:55	정지	1000.000	0.000	정상		확인
2022090061	2022-09-01 10:05:00	운행	1000.000	1.000	정상		확인
2022090062	2022-09-01 10:05:05	정지	1000.000	0.000	정상		확인
2022090063	2022-09-01 10:05:10	운행	1000.000	1.000	정상		확인
2022090064	2022-09-01 10:05:15	정지	1000.000	0.000	정상		확인
2022090065	2022-09-01 10:05:20	운행	1000.000	1.000	정상		확인
2022090066	2022-09-01 10:05:25	정지	1000.000	0.000	정상		확인
2022090067	2022-09-01 10:05:30	운행	1000.000	1.000	정상		확인
2022090068	2022-09-01 10:05:35	정지	1000.000	0.000	정상		확인
2022090069	2022-09-01 10:05:40	운행	1000.000	1.000	정상		확인
2022090070	2022-09-01 10:05:45	정지	1000.000	0.000	정상		확인
2022090071	2022-09-01 10:05:50	운행	1000.000	1.000	정상		확인
2022090072	2022-09-01 10:05:55	정지	1000.000	0.000	정상		확인
2022090073	2022-09-01 10:06:00	운행	1000.000	1.000	정상		확인
2022090074	2022-09-01 10:06:05	정지	1000.000	0.000	정상		확인
2022090075	2022-09-01 10:06:10	운행	1000.000	1.000	정상		확인
2022090076	2022-09-01 10:06:15	정지	1000.000	0.000	정상		확인
2022090077	2022-09-01 10:06:20	운행	1000.000	1.000	정상		확인
2022090078	2022-09-01 10:06:25	정지	1000.000	0.000	정상		확인
2022090079	2022-09-01 10:06:30	운행	1000.000	1.000	정상		확인
2022090080	2022-09-01 10:06:35	정지	1000.000	0.000	정상		확인
2022090081	2022-09-01 10:06:40	운행	1000.000	1.000	정상		확인
2022090082	2022-09-01 10:06:45	정지	1000.000	0.000	정상		확인
2022090083	2022-09-01 10:06:50	운행	1000.000	1.000	정상		확인
2022090084	2022-09-01 10:06:55	정지	1000.000	0.000	정상		확인
2022090085	2022-09-01 10:07:00	운행	1000.000	1.000	정상		확인
2022090086	2022-09-01 10:07:05	정지	1000.000	0.000	정상		확인
2022090087	2022-09-01 10:07:10	운행	1000.000	1.000	정상		확인
2022090088	2022-09-01 10:07:15	정지	1000.000	0.000	정상		확인
2022090089	2022-09-01 10:07:20	운행	1000.000	1.000	정상		확인
2022090090	2022-09-01 10:07:25	정지	1000.000	0.000	정상		확인
2022090091	2022-09-01 10:07:30	운행	1000.000	1.000	정상		확인
2022090092	2022-09-01 10:07:35	정지	1000.000	0.000	정상		확인
2022090093	2022-09-01 10:07:40	운행	1000.000	1.000	정상		확인
2022090094	2022-09-01 10:07:45	정지	1000.000	0.000	정상		확인
2022090095	2022-09-01 10:07:50	운행	1000.000	1.000	정상		확인
2022090096	2022-09-01 10:07:55	정지	1000.000	0.000	정상		확인
2022090097	2022-09-01 10:08:00	운행	1000.000	1.000	정상		확인
2022090098	2022-09-01 10:08:05	정지	1000.000	0.000	정상		확인
2022090099	2022-09-01 10:08:10	운행	1000.000	1.000	정상		확인
2022090100	2022-09-01 10:08:15	정지	1000.000	0.000	정상		확인

## Operation History and Issue Management

Systematic management of AMR operational history, including robot/fleet/failure event logs, providing insights for operation efficiency analysis. Helps quickly identify root causes and facilitates systematic issue resolution.



## Operation Statistics

Analyze AMR operational data daily, weekly, or monthly, and visualize individual robot performance through graphical representations.



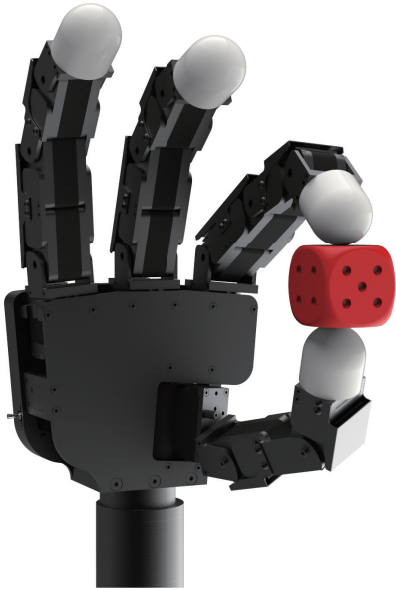
## Integrated IoT Monitoring and Control System

Collect real-time data systematically from all linked devices, enabling real-time status checks and direct control commands as needed.



## User-friendly GUI

Intuitive and user-friendly interface designed considering various operational environments and user types. Provides real-time operational information, easy AMR control, and swift interaction adjustments through the interface.



# Allegro Hand V4(4F)

- Light weight and portable anthropomorphic design
- cost-effective dexterous manipulation with applications in research and industry
- Multiple ready-to-use grasping algorithms  
Capable of handling a variety of object geometries

## Specification

Number of Fingers	Four(4) Fingers, Including Thumb	
Degrees of Freedom	4 Fingers x 4 = 16(Active)	
Actuation	Type Gear Ratio Max. Torque Max. Joint Speed	DC Motor 1:369 0.70(Nm) 0.11(sec/60 degree)
Weight	Finger Thumb Total	0.17kg 0.19kg 1.08kg
Joint Resolution	Measurement Resolution(Nominal)	Potentiometer 0.002 deg
Communication	Type Frequency	CAN 333Hz
Payload	5kg	
Power Requirement	12, 24Vdc / 100W	



# Allegro Hand V5(3F)

- Multiple ready-to-use grasping algorithms capable of handling a variety of object geometries
- 360-degree omnidirectional pressure-sensitive tactile sensor in the shape of a finger
- 9 independent current-controlled joints (3 Fingers x 3 DOF ea.)

## Specification

Number of Fingers	3 Fingers	
Degrees of Freedom	3 Fingers x 3 = 9(Active)	
Actuation	Type	DC Motor
	Gear Ratio	288.35:1 159.59:1 (2 <sup>nd</sup> Joint of a Finger)
	Stall Torque	0.92Nm 1.6Nm (2 <sup>nd</sup> Joint of a Finger)
	Nominal Torque	0.23Nm 0.48Nm (2 <sup>nd</sup> Joint of a Finger)
Payload	12kg(Depending on the Measurement Method)	
Weight	1,050g	
Joint Resolution	0.088deg	
Communication	Type	CAN, RS-485(Planned Support)
	Frequency	500Hz(CAN)
Power Requirement	24.0V / 5.0A / 120W	
Tactile Sensor(Optional)	Pressure Operating Range	30~125kPa
	Color Indicator	Returns '0' at atmospheric pressure(101.3 kPa) Blue: 0~124Pa Cyan: 125~249Pa Green: 250~375Pa Yellow: 376~500Pa Red: 500~24,000Pa
	Temperature Operating Range	-40~85°C
	Pressure Accuracy	6Pa



# Allegro Hand V5(4F) Plus

- Multiple ready-to-use grasping algorithms capable of handling a variety of object geometries
- 360-degree omnidirectional pressure-sensitive tactile sensor in the shape of a finger
- 16 independent current-controlled joints (4 Fingers x 4 DOF ea.)

## Specification

Number of Fingers	3 Fingers + 1 Thumb = 4	
Degrees of Freedom	4 Fingers x 4 = 16(Active)	
Actuation	Type	DC Motor
	Gear Ratio	288.35:1 576.7:1(2 <sup>nd</sup> Joint of the Finger Excluding the Thumb)
	Stall Torque	0.92Nm 1.84Nm(2 <sup>nd</sup> Joint of the Finger Excluding the Thumb)
	Nominal Torque	0.23Nm 0.46Nm(2 <sup>nd</sup> Joint of the Finger Excluding the Thumb)
Payload	15kg(Depending on the Measurement Method)	
Weight	1,024g	
Joint Resolution	0.088deg	
Communication	Type	CAN
	Frequency	500Hz(CAN)
Power Requirement	24.0V / 5.0A / 120W	
Tactile Sensor(optional)	Pressure Operating Range	30~125kPa
	Color Indicator	Returns '0' at Atmospheric Pressure(101.3 kPa) Blue: 0~124Pa Cyan: 125~249Pa Green: 250~375Pa Yellow: 376~500Pa Red: 500~24,000Pa
	Temperature Operating Range	-40~85°C
	Pressure Accuracy	6Pa



## **Contact Us.**

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